

GEOMETRIC PROPERTIES OF EXTENDED HOLOMORPHIC FUNCTIONS

Lidia Elena KOZMA

(Received 15.01.2002; revised 10.02.2002; accepted 10.03.2002)

Abstract. In this article I have determined some geometrical properties of the real surface $(S) \quad \vec{r} = \bar{i}y + \bar{j}u(x, y) + \bar{k}v(x, y)$ attached to a monogenic quaternion.

The notion of monogenic quaternion was introduced in [1] and represents a prolongement of the holomorphic functions in the four-dimension space. The difference between these holomorphic functions and the monogenic functions analyzed in [4] is the fact that the functions introduced in [1] can be particularized as holomorphic functions from the usual complex analysis. The analyzed geometrical properties: The Gauss Curvature, the curves' torsion on coordinates, the area of the holomorphic surface element. The notion of monogenic quaternion given under relation (1) as well as its properties constitute the author's original contribution.

MSC: 32A38

Keywords: quaternion type function, generalized monogeneity conditions, geometric properties

(1) We take a quaternion type function of two real variables,

$$\mathcal{K}(x, y) = P(x, y) + iQ(x, y) + jR(x, y) + kS(x, y) \in D \subset \mathbb{R}^2 \rightarrow \mathcal{C}$$

\mathcal{C} = the quaternion's set ((x, y) = pair of real variables), which we choose wishing to extend the complex numbers and the Cauchy-Riemann monogeneity conditions of form [1].

$$\mathcal{K}(x, y) = x + iy + ju(x, y) + kv(x, y) \quad (1)$$

(2) where

$$\begin{aligned} i^2 &= -j^2 = k^2 = +1 \\ ij &= k; \quad ki = j; \quad j \cdot k = i \\ ji &= -k; \quad ik = -j; \quad kj = -i \end{aligned}$$

We showed in [1] that this function verifies the following conditions:

$$\begin{aligned} (1) \quad \frac{\partial \mathcal{K}}{\partial x} &= (1, 0, u_x, v_x) \quad \text{and} \quad \frac{\partial \mathcal{K}}{\partial y} = (0, 1, u_y, v_y) \quad (2) \\ \frac{\partial \mathcal{K}}{\partial y} &= (0, 1, u_y, v_y) \quad \text{and} \quad \frac{\partial \mathcal{K}}{\partial x} = (1, 0, u_x, v_x) \end{aligned}$$

If $\mathcal{K}(x, y) \in C^2(\mathbb{R}^2)$ and we use the Cauchy-Riemann's conditions for functions $w(x, y) = (u(x, y), v(x, y))$

$$\begin{aligned} \frac{\partial u}{\partial x} &= \frac{\partial v}{\partial y} \\ \text{COMPLEX DIFFERENTIAL PROPERTIES OF} \\ \text{EXTENDED HOMOGENEOUS FUNCTIONS} \end{aligned}$$

with $\Delta u = 0$ and $\Delta v = 0$ we obtain for the coaternion $\mathcal{K}(x, y)$ given by relation (1) the following monogeneity conditions

$$\left\{ \begin{array}{l} \text{condition one: } \frac{\partial \mathcal{K}}{\partial x} + i \frac{\partial \mathcal{K}}{\partial y} = i [1 + (u_x)^2 + (v_y)^2] = i [1 + (v_x)^2 + (v_y)^2], \\ \text{condition two: } \frac{1}{2} \left(\frac{\partial \mathcal{K}}{\partial x} + i \frac{\partial \mathcal{K}}{\partial y} \right) = (1, 0, u_x - v_y, v_x + u_y) = (1, 0, 0, 0) = \text{scalar}, \\ \text{condition three: } \frac{1}{2} \left(\frac{\partial \mathcal{K}}{\partial x} - i \frac{\partial \mathcal{K}}{\partial y} \right) = (0, 0, \frac{1}{2}(u_x + v_y), \frac{1}{2}(v_x - u_y)) \text{ must be zero and} \\ \text{then: } u_x + v_y = 0 \text{ and } v_x - u_y = 0 \text{ (extensio} \end{array} \right. \quad (3)$$

Observations: The first condition in (3) will be considered a monogeneity condition for the cuaternion $\mathcal{K}(x, y)$. The conditions two and three in relation (3) can be regarded as extensio

We take the surface

$$(S) \text{data} \bar{r} = iy + \bar{j}u(x, y) + \bar{k}v(x, y) \text{ at point } z \in \mathbb{C} \quad (4)$$

which is a vector (quaternion reduced to vector) $(0, 0, 0) + (0, 0, 1)Q + (0, 0, 0)A = (0, 0, 1)$ or $\bar{r} = (0, 0, 1)$ and in this case $\bar{r}_x = (0, u'_x, v'_x)$, $\bar{r}_y = (1, u'_y, v'_y)$ and in conclusion $\bar{r}_x + \bar{r}_y = (0, 0, 0)$ (scalar + vectorial function)

Let's further analyse some geometric properties of this surface (S) from relation (4):

$$\begin{aligned} \bar{r}_x &= (0, u'_x, v'_x) \quad \bar{r}_x \times \bar{r}_y = \bar{i} \frac{D(u, v)}{D(x, y)} + \bar{j} \cdot u'_x - \bar{k} \cdot v'_x \\ \bar{r}_y &= (1, u'_y, v'_y) \end{aligned} \quad (5)$$

In Cauchy-Riemann's monogeneity conditions then =

$$\bar{r}_x \times \bar{r}_y = \bar{i} \frac{D(u, v)}{D(x, y)} - \bar{j} \cdot u'_y - \bar{k} \cdot v'_y \quad (6)$$

We calculate $EG - F^2$ for surface (S) given by (4)

$$\begin{aligned} E &= (u'_x)^2 + (v'_x)^2; \\ F &= 0; \quad (0, 0, 0, 1) = \frac{AB}{CD} \\ G &= 1 + u'^2_x + v'^2_y \\ EG - F^2 &= (u'_x)^2 + (v'_x)^2 + (u'_y v'_x + u'_x v'_y)^2 \end{aligned} \quad (7)$$

If K is a monogenous function, then

$$EG - F^2 = |\vec{r}_x \times \vec{r}_y|^2 = K \quad (8)$$

Co-ordinate curves on (S)

The tangents to the co-ordinate curves will be respectively

$$\begin{aligned} \vec{r}_{x_0} &= \vec{i}y + \vec{j}u(x_0, y) + \vec{k}v(x_0, y) \\ \vec{r}_{y_0} &= \vec{i}y_0 + \vec{j}u(x, y_0) + \vec{k}v(x, y_0) \end{aligned} \quad (9)$$

$$\left\{ \begin{array}{l} \vec{T}_{x_0} = (0, u'_y, v'_y) \\ \vec{T}_{y_0} = (1, u_x, v_x) \end{array} \right. \quad (10)$$

We find that $\vec{T}_{x_0} \cdot \vec{T}_{y_0} = 0 + u'_x u'_y + v'_x v'_y = 0$ in the monogeneity case, thus $\vec{T}_{x_0} \perp \vec{T}_{y_0}$; the co-ordinate curves are orthogonal for $F \equiv 0$, and the first fundamental form of the surface is $ds^2 = EG - F^2 = EG$.

The co-ordinate curves' network constitutes an isotherm network (isotherm system), and about metrics $ds^2 = \lambda(x, y)[(dx)^2 + (dy)^2]$ where $\lambda(x, y) = \frac{1}{(du)^2 + (dv)^2}$ we say that it has an isotherm form in the monogeneity case [4].

The area of a surface portion

$$\sigma = \iint_D \sqrt{EG - F^2} dx dy = \iint_D \left| \frac{u'_x}{v_x} - \frac{u'_y}{v_y} \right| dx dy = \text{Area}(S).$$

The differential equation of the geodesic lines of surface (S) is $(\vec{N}, d\vec{r}, d^2\vec{r}) = 0$ where $\vec{N} = \vec{r}_x \times \vec{r}_y$ thus $\vec{N}(u_x v_y - u_y v_x, v_x, -u_x) = 0$

$$\left\{ \begin{array}{l} x_0 = (1, 0, u_{x_0}, v_{x_0}) \\ r_y = (0, 1, u_y, v_y) \end{array} \right. \quad (1)$$

$$\begin{aligned} r_{x^2}'' &= (0, 0, u_{x^2}, v_{x^2}) \\ r_{y^2}'' &= (0, 0, u_{y^2}, v_{y^2}) \\ r_{xy}'' &= (0, 0, u_{xy}, v_{xy}) = r_{yx}'' \end{aligned} \quad (2)$$

The Gauss Curvature

In the case when $F = 0$ for surface (S) , the Gauss curvature can be calculated [4] with the following formula

$$(5) \quad K = -\frac{1}{2E} \left[\left(\frac{E_u}{E} \right)_v + \left(\frac{E_v}{E} \right)_u \right].$$

For the surface considered in (4) the Gauss curvature is (see [3]) for surfaces with a izoterm metrics:

$$(6) \quad ds^2 = E(dx^2 + dy^2)$$

$$K = -\frac{1}{2E} \left[\left(\frac{E_x}{E} \right)_y + \left(\frac{E_y}{E} \right)_x \right].$$

(6) Making the calculations:

$$E_x^2 + E_y^2 = 2[(u''_{xx})^2 + (u''_{yy})^2 + 2(u''_{xy})^2].$$

We obtain

$$(u''_{xx})^2 - (u''_{yy})^2 = (u''_{xx} - u''_{yy})(u''_{xx} + u''_{yy}) = 0$$

and

$$\begin{aligned} \left(\frac{E_x}{E} \right)_y + \left(\frac{E_y}{E} \right)_x &= \frac{1}{E^2} \{ E [E_{xx}^2 + E_{yy}^2] - (E_x)^2 - (E_y)^2 \} = \\ &= \frac{1}{E^2} \{ -2(u'_x)^2(u''_{xx})^2 - 2(u'_y)^2(u''_{yy})^2 + 2(u''_{xy})^2 \cdot (u'_y)^2 + 2(u''_{xy})^2 \cdot (u'_x)^2 \} = \\ &= \frac{2}{E^2} \{ (u'_y)^2 [(u''_{xx})^2 - (u''_{yy})^2] + (u'_x)^2 [(u''_{yy})^2 - (u''_{xx})^2] \} = \\ 0 &= (u'_y)^2 \cdot \frac{[(u''_{xx})^2 - (u''_{yy})^2]}{E^2} \cdot [(u'_x)^2 - (u'_y)^2] = 0 \end{aligned}$$

On this surface (S) $\bar{r} = iy + ju(x, y) + kv(x, y)$ in conditions $[C - R]$ of monogeneity the curvature Gauss = 0. (for surfaces with a izoterm metrics).

The calculation of curves' torsion on surface

The surface (S)

$$\bar{r} = iy + ju(x, y) + kv(x, y) \quad (4)$$

attached to the quaternion $K = x + \bar{r}$ allows the curves on surface

$$r_x = (0, u'_x, v'_x)$$

the curves' curvatures $r_y = (1, u'_y, v'_y)$ (the tot $t = 3$ with respect to the channel growths)

and $\left(\frac{1}{T}\right)_{y_0} = \frac{1}{A^2 + B^2 + C^2} \begin{vmatrix} 0 & u'_x & v'_x \\ 0 & u''_{x^2} & v''_{x^2} \\ 0 & u'''_{x^3} & v'''_{x^3} \end{vmatrix} = 0$

The curve $y = y_0 = \text{constant}$ is of null torsion, thus the curve is plane.

The curve $x = x_0 = \text{constant}$ has the torsion

$$\left(\frac{1}{T}\right)_{x_0} = \frac{1}{A^2 + B^2 + C^2} \begin{vmatrix} 0 & u'_y & v'_y \\ 0 & u''_{y^2} & v''_{y^2} \\ 0 & u'''_{y^3} & v'''_{y^3} \end{vmatrix} = \frac{1}{|\mathbf{N}|^2} [u''_{y^2} v'''_{y^3} - u'''_{y^3} v''_{y^2}] \neq 0. \quad (1)$$

Usually the ratio of the torsions between coordinate curves is called the curvature ratio.

The curvature of co-ordinate curves

$$R = \frac{|\mathbf{r}' \times \mathbf{r}''|}{|\mathbf{r}'|^3}. \quad (2)$$

Let there be $y = y_0$

$$\begin{aligned} \mathbf{r}_x &= (0, u'_x, v'_x) \quad ; \quad \mathbf{r}'_x \times \mathbf{r}''_{x^2} = \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ 0 & u'_x & v'_x \\ 0 & u''_{x^2} & v''_{x^2} \end{vmatrix} = \bar{i}(u'_x v''_{x^2} - v'_x u''_{x^2}), \\ \mathbf{r}_y &= (1, u'_y, v'_y) \quad ; \quad \mathbf{r}'_y \times \mathbf{r}''_{y^2} = \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ 0 & u'_y & v'_y \\ 0 & u''_{y^2} & v''_{y^2} \end{vmatrix} = \bar{i}(u'_y v''_{y^2} - v'_y u''_{y^2}), \\ K_m &= \frac{|u'_x v''_{x^2} - v'_x u''_{x^2}|}{[(u'_x)^2 + (v'_x)^2]^{3/2}}. \end{aligned}$$

The curve $x = x_0$ has

$$\begin{aligned} \mathbf{r}'_y &= (1, u'_y, v'_y) \quad ; \quad \mathbf{r}'_y \times \mathbf{r}''_{y^2} = \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ 0 & u'_y & v'_y \\ 0 & u''_{y^2} & v''_{y^2} \end{vmatrix} = \bar{i}(u'_y v''_{y^2} - v'_y u''_{y^2}) - \bar{j} \cdot v''_{y^2} + \bar{k} u''_{y^2}, \\ \mathbf{r}_x &= (0, u'_x, v'_x) \quad ; \quad \mathbf{r}'_x \times \mathbf{r}''_{x^2} = \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ 0 & u'_x & v'_x \\ 0 & u''_{x^2} & v''_{x^2} \end{vmatrix} = \bar{i}(u'_x v''_{x^2} - v'_x u''_{x^2}). \end{aligned}$$

$$K_{x_0} = \frac{\sqrt{(u'_y v''_{y^2} - v'_y u''_{y^2}) + (v''_{y^2})^2 + (u''_{y^2})^2}}{\left[\sqrt{1 + (u'_y)^2 + (v'_y)^2}\right]^3} = \frac{\sqrt{\left[\left(\frac{v_y}{u_y}\right)'_y\right]^2 + (v''_{y^2})^2 + (u''_{y^2})^2}}{G^{3/2}}$$

We find that the curvatures of co-ordinate curves are not constant, although the Gauss curvature defined [3] as product of two curvatures of co-ordinate curves is variable (K_{\max}) (K_{\min}).

Generally, curves $x = x_0$ and $y = y_0$ are not straight ($K_{x_0} \neq 0, K_{y_0} \neq 0$). In the monogeneity case

$$(K_{max})(K_{min}) = 0 \equiv \text{The Gauss Curvature.}$$

REFERENCES

- [1] Lidia Elena KOZMA, *The corollary differential of Pompei for holomorphic functions of quaternion type*, (PC-137) Pamm's Conference Balaton Almady 23-26 May 2002 (Traditional Yearly Main Conference)
- [2] Andrei DOBRESCU, *Differential Geometry*, Didactic and Pedagogic Publishing, Bucharest, 1963
- [3] Tristan NEEDHAM, *Visual complex Analysis*, Clarendon Press-Oxford, reprint 1997, 1998
- [4] Marcel ROŞCULEȚ, *Monogenic functions on associative and non-commutative algebras*, Technical Publishing, Bucharest, 1997

Received: 6. 05. 2002

Department of Mathematics and Computer Science
North University of Baia Mare,
Victoriei 76, 4800, Romania
E-mail: lidik@ubm.ro